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Author: Małgorzata Rozmus-Chmura

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Ministerstwo Nauki i Szkolnictwa Wyższego

MALGORZATA ROZMUS-CHMURA

REGULAR SOLUTIONS OF SOME FUNCTIONAL EQUATIONS IN THE INDETERMINATE CASE

Abstract. The paper deals with the existence and uniqueness of regular solutions of the equation $\varphi(x) = h(x, \varphi(f(x)))$. Also in the indeterminate case the existence of solutions of $\varphi(f(x)) = g(x, \varphi(x))$ is studied.

In the present paper we shall consider the following functional equations

(1)
$$\varphi(x) = h(x, \varphi[f(x)]),$$

(2)
$$\varphi[f(x)] = g[x, \varphi(x)],$$

where $\varphi: I = [0, a) \rightarrow R$, $0 < a \leq \infty$ is an unknown function.

The phrase regular solution used in the title will have the following meaning: "a solution which is continuous in the whole interval I and possesses a right-side derivative at the point zero".

The problem of regular solutions of linear functional equations is contained in [1] and [2]. The theory of continuous solutions of equations (1) and (2) has been developed in [4], [5], [6], [7], [8].

§ 1. Let I be an interval [0, a), $0 \le a \le \infty$ and let Ω be a neighbourhood of $(0, 0) \in \mathbb{R}^2$. Assume that the given functions f, g and h fulfil the following conditions.

(i) The function $f: I \to R$ is continuous, strictly increasing, there exists $f'(0+) \neq 0$ and $0 \leq f(x) \leq x$ in $I \setminus \{0\}$.

(ii) The function $h: \Omega \to R$ is continuous, there exist c > 0, d > 0 and a continuous function $\gamma: [0, c) \subset I \to R$ such that

(3)
$$|h(x, y_1)-h(x, y_2)| \leq \gamma(x) |y_1-y_2| \text{ in } U \cap \Omega,$$

where $U: 0 \leq x \leq c$, $|y| \leq d$. Moreover, there exist A and B such that

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$$h(x, y) = Ax + By + R(x, y),$$

where

(5)
$$R(x, y) = o\left(\sqrt{x^2 + y^2}\right), (x, y) \to (0, 0).$$

For every $x \in I$ we denote

$$(6) \qquad \qquad \Omega_x := \{y : (x, y) \in \Omega\}$$

and

 $\Lambda_x := \{h(x, y) : y \in \Omega_x\}.$

(iii) For every $x \in I$, Ω_x is an open interval and $\Lambda_{f(x)} = \Omega_x$.

(iv) The function $g: \Omega \to R$ is continuous for every $x \in I$. For every fixed $x \in I$ the function g as a function of y is invertible. There exist c > 0, d > 0 and a continuous function $\gamma: [0, c) \subset I \to R$ such that

(7)
$$|g(x, y_1) - g(x, y_2)| \leq \gamma(x) |y_1 - y_2|$$
 in $U \cap \Omega$,

where $U: 0 \le x \le c$, $|y| \le d$ and γ has a positive bound in [0, c). Moreover, there exist A and $B \ne 0$ such that

(8)
$$g(x, y) = Ax + By + R(x, y),$$

where

$$\mathcal{R}(x, y) = o\left(\sqrt{x^2 + y^2}\right), \ (x, y) \to (0, 0).$$

For every $x \in I$ we denote

$$V_x := \{g(x, y) : y \in \Omega_x\},\$$

where Ω_x is given by (6).

(v) For every $x \in I$, Ω_x is an open interval and $V_x = \Omega_{f(x)}$. The indeterminate case

(9)
$$f'(0) \gamma(0) = 1$$

for equation (1) and

(10)
$$\frac{f'(0)}{\gamma(0)} = 1$$

for equation (2) will be considered in this paper.

§ 2. Let us consider equation (1) and let $\varphi(x) = x \psi(x)$. Then equation (1) is of the form

(11)
$$\psi(x) = H(x, \varphi[f(x)]),$$

where

(12)
$$H(x, z) := \begin{cases} \frac{1}{x} h(x, f(x) z), & \text{for } x \neq 0 \\ A + B f'(0) z, & \text{for } x = 0 \end{cases}$$

is defined in the set

$$\Omega^1 = \{(x, z) : (x, f(x) z) \in \Omega\}.$$

For an arbitrary $x \in I$ we denote

$$\begin{split} \mathcal{Q}_x^{\mathbf{i}} &:= \{ z: (x,z) \in \mathcal{Q}^{\mathbf{i}} \} \\ \mathcal{A}_x^{\mathbf{i}} &:= \{ H(x,z) : z \in \mathcal{Q}_x^{\mathbf{i}} \}. \end{split}$$

and

(a) H is continuous in a neighbourhood of the point $(0, \eta)$, where η is arbitrary constant.

(b) For every η , there exist a $\delta \in (0, c]$ and a $d_1 > 0$ such that

(13)
$$|H(x, z_1) - H(x, z_2)| \leq \gamma_1(x) |z_1 - z_2|$$
 for $x \in [0, \delta), |z - \eta| \leq d_1$,

. . . .

where

(14)
$$\gamma_1(x) = \begin{cases} \frac{f(x)}{x} & \gamma(x), \text{ for } x \in (0, \delta) \\ 1, & \text{ for } x = 0 \end{cases}$$

is a continuous function.

(c) For every $x \in I$, Ω_x^1 is an open interval and $\Lambda_{f(x)}^1 \subset \Omega_x^1$.

P r o o f. Ad (a). It suffices to show, that the function H is continuous at the point $(0, \eta)$. We have

$$\lim_{\substack{x \to 0^+ \\ z \to \eta}} H(x, z) = \lim_{\substack{x \to 0^+ \\ z \to \eta}} \frac{1}{x} h[x, f(x) z] = \lim_{\substack{x \to 0^+ \\ z \to \eta}} \left[A + B \frac{f(x)}{x} z + \frac{1}{x} R(x, f(x) z) \right].$$

From (5) we obtain

$$\lim_{\substack{x \to 0^+ \\ z \to \eta}} \frac{R(x, f(x) z)}{\sqrt{x^2 + [f(x) z]^2}} = 0$$

whereas (i) implies

$$\frac{R(x,f(x)z)}{\sqrt{x^2+[f(x)z]^2}} \bigg| \ge \bigg| \frac{R(x,f(x)z)}{x\sqrt{1+z^2}} \bigg|.$$

Therefore,

$$\lim_{\substack{x \to 0^+ \\ z \to \eta}} H(x, z) = A + B f'(0) \eta = H(0, \eta),$$

which finishes our proof in case (a).

Ad (b). The function f is continuous and f(0) = 0; thus there exist a $\delta \in (0, c]$ and a $d_1 > 0$ such that for every $x \in (0, \delta)$ and $|z-\eta| < d_1$ the inequality |f(x) z| < d holds. Therefore, the inequality

$$|H(x, z_1) - H(x, z_2)| = \left| \frac{1}{x} [h(x, f(x) z_1) - h(x, f(x) z_2)] \right| \leq \frac{f(x)}{x} \gamma(x) |z_1 - z_2| \text{ for } x \neq 0$$

holds and

$$|H(0, z_1) - H(0, z_2)| = |B| f'(0) |z_1 - z_2|.$$

From (3) we have

 $|B| = |h_y(0, 0)| \leq \gamma(0).$

Consequently,

$$|B| f'(0) \leq \gamma(0) f'(0) = 1.$$

Condition (13) is fulfilled with the function γ_1 given by formula (14). We have also

$$\lim_{x\to 0} \frac{f(x)}{x} \gamma(x) = f'(0)\gamma(0) = 1.$$

This implies that
$$\gamma_1$$
 is continuous in $[0, c)$.

Ad (c). We may assume that Ω is of the form

$$\Omega: \begin{cases} 0 \leq x < a \\ a_1(x) < y < a_2(x), \end{cases}$$

where $a_1(x) \leq 0$ and $a_2(x) \geq 0$ for $x \in [0, a)$. It is easily seen that

$$\Omega^{1}: \begin{cases} 0 \leq x < a \\ \frac{a_{1}(x)}{f(x)} < z < \frac{a_{2}(x)}{f(x)} \text{ for } x \neq 0 \\ z \text{ is arbitrary for } x = 0. \end{cases}$$

In particular, we have $\Omega_0^1 = (-\infty, +\infty)$ whence $\Lambda_{f(0)}^1 \subset \Omega_0^1$. For $x \neq 0$ we have

$$A_{f(x)}^{1} = \{v : v = H [f(x), z], z \in \Omega_{f(x)}^{1}\} = \\ = \left\{v : v = \frac{1}{f(x)} h [f(x), f^{2}(x) z], z \in \left(\frac{a_{1}[f(x)]}{f^{2}(x)}, \frac{a_{2}[f(x)]}{f^{2}(x)}\right)\right\} = \\ \equiv \{v : f(x) v = h[f(x), y], y \in (a_{1}[f(x)], a_{2}[f(x)]) = \Omega_{f(x)}\}.$$

From (iii) we obtain

$$\Lambda_{f(x)} = \{h \ [f(x), y] : y \in \Omega_{f(x)}\} \subset \Omega_x$$

whence

$$\frac{a_1(x)}{f(x)} < v < \frac{a_2(x)}{f(x)}.$$

Therefore

$$A_{f(x)}^{1} \subset \left(\frac{a_{1}(x)}{f(x)}, \frac{a_{2}(x)}{f(x)}\right) = \Omega_{x}^{1}.$$

The proof of Lemma 1 is complete.

From Lemma 1 and condition (11) we obtain.

LEMMA 2. We assume (i), (ii), (iii)). If ψ is a continuous solution of equation (11) in I, then $\varphi(x) = x \psi(x)$ is a regular solution of equation (1)

in I and such that $\varphi(0) = 0$. If φ is a regular solution of equation (1) in I and such that $\varphi(0) = 0$ and $\varphi'(0) = \eta$, then the function

$$\psi(x) = \begin{cases} \frac{\varphi(x)}{x} & \text{for } x \neq 0 \\ \varphi'(0) & \text{for } x = 0 \end{cases}$$

yields a continuous solution of equation (11) in I such that $\psi(0) = \eta$.

The uniqueness of regular solutions depends essentially on the behaviour of the sequence

(15)
$$\Gamma_n(x) := \prod_{i=0}^{n-1} \gamma_i[f^i(x)],$$

where γ_1 is defined by (14).

THEOREM 1. We assume (i), (ii) (iii) and (9). Let η be an arbitrary constant. If there exist an M > 0 and a $\delta_1 \in (0, \delta]$ (where δ is the constant from Lemma 1) such that

$$\Gamma_n(x) \leq M, \ n = 0, 1, ... \ for \ x \in [0, \delta_1),$$

then equation (1) has at most one regular solution in I fulfilling conditions $\varphi(0) = 0$, $\varphi'(0) = \eta$.

Proof. From our hypotheses and from Lemma 1 it follows that the assumptions of Theorem 1 from [4] are fulfilled. Thus equation (11) has at most one continuous solution in I fulfilling the condition $\psi(0) = \eta$. Now, our assertion results from Lemma 2.

REMARK 1. If equation (11) has a continuous solution, then

$$(16) H(0, \eta) = \eta.$$

The definition of function H implies that equation (16) assumes the form

$$A+Bf'(0)\eta=\eta.$$

Let

(17)
$$\mathcal{H}(x) := |H(x, \eta) - \eta| = \begin{cases} \left| \frac{1}{x} h[x, f(x) \eta] - \eta \right| & \text{for } x \neq 0 \\ 0 & \text{for } x = 0. \end{cases}$$

THEOREM 2. We assume (i), (ii), (iii) and condition (9). If (for a fixed η fulfilling equation (16)) there exists a $\delta_2 > 0$ such that

(18)
$$\sum_{n=0}^{\infty} \Gamma_n(x) \mathcal{H} [f^n(x)]$$

is uniformly convergent in $[0, \delta_2)$ then equation (1) has a regular solution in I fulfilling conditions $\varphi(0) = 0$, $\varphi'(0) = \eta$.

Proof. From the hypotheses of our theorem and from Lemma 1 it follows that the assumptions of Theorem 3 from [4] concerning equa-

tion (11) are satisfied. Consequently, equation (11) possesses a continuous solution in I fulfilling the condition $\psi(0) = \eta$. Now, our assertion results from Lemma 2.

§ 3. If we put $\varphi(x) = x \psi(x)$ in equation (2), then we come to

(19)
$$\psi[f(x)] = K[x, \psi(x)],$$

where the function

(20)
$$K(x,z) = \begin{cases} \frac{1}{f(x)} g(x,xz) & \text{for } x \neq 0 \\ \frac{A}{f'(0)} + \frac{B}{f'(0)} z & \text{for } x = 0 \end{cases}$$

is defined in the region

 $\Omega^2 = \{(x, z) : (x, xz) \in \Omega\}.$

For any fixed $x \in I$ we put

$$\varOmega^{\mathbf{2}} = \{ y : (x, y) \in \Omega^{\mathbf{2}} \}$$

and

$$\mathbf{V}_{\boldsymbol{x}}^2 = \{ K(\boldsymbol{x}, \boldsymbol{z}) : \boldsymbol{z} \in \Omega_{\boldsymbol{x}}^2 \}.$$

LEMMA 3. Suppose that assumptions (i), (iv), (v) and condition (10) are satisfied. Then the function K(x, z) fulfils the following conditions:

(a) K(x, z) is continuous in a neighbourhood of each point $(0, \eta)$, where η is an arbitrary constant.

(b) For every real η there exist constants $\delta \in (0, c]$ and $d_1 > 0$ such that

(21)
$$|K(x, z_1) - K(x, z_2)| \leq \gamma_1(x) |z_1 - z_2|$$
 for $0 \leq x < \delta, |z - \eta| < d_1$,

wher**e**

(22)
$$\gamma_1(x) = \begin{cases} \frac{x}{f(x)} & \gamma(x) \text{ for } x \in (0, \delta) \\ 1 & \text{ for } x = 0 \end{cases}$$

is a continuous function.

(c) For every $x \in I$ the set Ω_x^2 is an open interval and $V_x^2 = \Omega_{f(x)}^2$.

(d) For any fixed $x \in I$ the function K(x, z) is invertible with respect to z.

Proof. Ad (a). In order to prove that K(x, z) is continuous it suffices to show its continuity at a point $(0, \eta)$;

$$\lim_{\substack{x \to 0+\\z \to \eta}} K(x,z) = \lim_{\substack{x \to 0+\\z \to \eta}} \frac{1}{f(x)} g(x,xz) =$$
$$= \lim_{\substack{x \to 0+\\z \to \eta}} \left[A \frac{x}{f(x)} + B \frac{x}{f(x)} z + \frac{1}{f(x)} R(x,xz) \right].$$

Hypothesis (8) implies

$$\lim_{\substack{x \to 0+\\ z \to \eta}} \frac{R(x, xz)}{x \sqrt{1+z^2}} = 0,$$

whence

$$\lim_{\substack{x\to 0^+\\z\to \eta}}\frac{1}{f(x)}R(x,xz)=\lim_{\substack{x\to 0^+\\z\to \eta}}\frac{R(x,xz)}{x}\cdot\frac{x}{f(x)}=0.$$

Consequently

$$\lim_{\substack{x \to 0^+ \\ z \to \eta}} K(x, z) = \frac{A}{f'(0)} + \frac{B}{f'(0)} \eta = K(0, \eta),$$

which finishes the proof of (a).

Ad (b). Evidently, for every real η one can find a $\delta \in (0, c]$ and a positive d_1 such that the inequality |xz| < d is satisfied whenever $x \in (0, \delta)$ and $|z-\eta| < d_1$. Applying condition (7) we get

$$|K(x, z_1) - K(x, z_2)| = \left| \frac{1}{f(x)} \left[g(x, xz_1) - g(x, xz_2) \right] \right| \leq \frac{x}{f(x)} \gamma(x) |z_1 - z_2| \text{ for } x \neq 0.$$

For x = 0 we have

$$|K(0, z_1) - K(0, z_2)| = \frac{|B|}{f'(0)} |z_1 - z_2|.$$

Condition (7) implies also that

$$|B| = |g_y(0, 0)| \leq \gamma(0).$$

Since 0 < f(x) < x, we have $f'(0) = \lim_{x \to 0} \frac{f(x)}{x} > 0$, because $f'(0) \neq 0$ by assumption. Consequently, on account of (10) we have

$$\frac{|B|}{f'(0)} \leq \frac{\gamma(0)}{f'(0)} = 1.$$

This proves that condition (21) is satisfied with $\gamma_1(x)$ defined by (22). Since

$$\lim_{x \to 0^+} \frac{x}{f(x)} \gamma(x) = \frac{\gamma(0)}{f'(0)} = 1,$$

the function $\gamma_1(x)$ is continuous in $[0, \delta)$ which completes the proof of condition (b).

Ad (c). We may assume that the domain Ω has the form

$$\Omega: \begin{cases} 0 \leq x < a \\ \alpha_1(x) < y < \alpha_2(x) \end{cases}$$

where $a_1(x) < 0$ and $a_2(x) > 0$. It is easy to check that, in such a case, the region Ω^2 is of the form

$$\Omega^{2}: \begin{cases} 0 \leq x \leq a \\ \frac{a_{1}(x)}{x} < z < \frac{a_{2}(x)}{x} & \text{for } x \neq 0, \\ z \text{ is arbitrary} & \text{for } x = 0. \end{cases}$$

Since f(0) = 0 we have $\Omega_{f(0)}^2 = \Omega_0^2 = (-\infty, \infty)$. On the other hand

$$K(0,z) = \frac{A}{f(0)} + \frac{B}{f(0)}z$$
, whence $V_0^2 = (-\infty,\infty)$

i.e. $V_0^2 = \Omega_{f(0)}^2$. For $x \neq 0$ we have

$$V_x^2 = \left\{ v : v = \frac{1}{f(x)} g(x, xz), z \in \left(\frac{a_1(x)}{x}, \frac{a_2(x)}{x}\right) \right\} = \\ = \left\{ v : f(x) \ v = g(x, y), \ y \in \Omega_x \right\}.$$

Assumption (v) implies

$$\{f(x) v : f(x) v = g(x, y), y \in \Omega_x\} = (a_1[f(x)], a_2[f(x)])$$

whence

$$V_x^2 = \left(\frac{a_1[f(x)]}{f(x)}, \frac{a_2[f(x)]}{f(x)}\right) = \Omega_{f(x)}^2$$

which proves our assertion (c).

Ad (d). Since $K(0, z) = \frac{A}{f'(0)} + \frac{B}{f'(0)}z$ and $B \neq 0$ by assumption, function K(0, z) is invertible. For $x \neq 0$ the function K(x, z) is a one-toone mapping with respect to z because g(x, y) is invertible as a function

of the second variable (with an arbitrarily fixed $x \in I$). This proves (d). The following lemma is a simple consequence of equation (19) and

Lemma 3.

LEMMA 4. Assume (i), (iv) and (v). If ψ is a continuous solution of equation (19) then the function $\varphi(x) = x \psi(x)$ is a regular solution of equation (2) fulfilling the condition $\varphi(0) = 0$. If φ is a regular solution of equation (2) in I such that $\varphi(0) = 0$ and $\varphi'(0) = \eta$, then the function

$$\psi(x) = \begin{cases} \frac{\varphi(x)}{x} & \text{for } x \neq 0 \\ \varphi'(0) & \text{for } x = 0 \end{cases}$$

is a continuous solution of (19) fulfilling the condition $\psi(0) = \eta$.

Let $\Gamma_n(x)$ be defined by formula (13) where $\gamma_1(x)$ is given by (22). THEOREM 3. Assume (i), (iv), (v) and condition (10). Moreover, suppose that there exists an interval $J \subset I$ such that $\Gamma_n(x)$ tends to zero uniformly on J. Then a regular solution of equation (2) fulfilling the conditions $\varphi(0) = 0$ and $\varphi'(0) = \eta$, depends on an arbitrary function.

Proof. On account of our assumptions and by means of Lemma 3 we infer that the assumptions of Theorem 6 from [4] concerning equa-

tion (19) are satisfied. Thus a continuous solution ψ of (19) fulfilling the condition $\psi(0) = \eta$ (if such a solution exists) depends on an arbitrary function. Now, Lemma 4 completes our proof.

Condition

$$(23) K(0,\eta) = \eta$$

is necessary for equation (19) to have a continuous solution with $\psi(0) = \eta$.

REMARK 2. The definition of K(x, z) implies that equation (23) has the form

$$\frac{A}{f'(0)}+\frac{B}{f'(0)}\eta=\eta.$$

Put

(24)
$$X(x) := |K(x, \eta) - \eta| = \left| \left| \frac{1}{f(x)} g(x, x\eta) - \eta \right| \text{ for } x \neq 0 \\ 0 \text{ for } x = 0,$$

where η is a solution of (23) and

(25)
$$H_n(x) := \sum_{\substack{i=0\\i=1}}^{n-2} \frac{\mathcal{K}[f^i(x)]}{\Gamma_{i+1}(x)} \Gamma_n(x), n = 2, 3, ...$$

THEOREM 4. Assume (i), (iv), (v) and condition (10). If, for a fixed η , there exists a point $x_0 \in \Gamma \setminus \{0\}$ such that both $\Gamma_n(x)$ and $H_n(x)$ tend to zero uniformly on $[f(x_0), x_0]$, then equation (2) has a regular solution φ in I fulfilling the conditions $\varphi(0) = 0$ and $\varphi'(0) = \eta$, depending on an arbitrary function.

Proof. The assumptions of our theorem and Lemma 3 imply that the hypotheses of Theorem 7 from [4] concerning equation (19) are satisfied. Consequently, equation (19) has a continuous solution ψ in I fulfilling the condition $\psi(0) = \eta$ and depending on an arbitrary function. Now our assertion results from Lemma 4.

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